Autonomous mobility



Brno University of Technology Faculty of Information Technology

Martin Jírovec Technology transfer jirovec@vutbr.cz www.fit.vutbr.cz

> BRNO FACULTY UNIVERSITY OF INFORMATION OF TECHNOLOGY TECHNOLOGY



BRNO UNIVERSITY OF TECHNOLOGY

ini iii

-

- 1899 founded
- 8 faculties

111 111 111 111

- 18,000 students
 - 1,500 PhD students

Faculty of Civil Engineering Faculty of Mechanical Engineering Faculty of Electrical Engineering and Communication **Faculty of Architecture** Faculty of Chemistry Faculty of Business and Management **Faculty of Fine Arts** Faculty of Information Technology Institute of Forensic Engineering Centre of Sports Activities Central European Institute of Technology **SIX Research Centre**



FACULTY OF INFORMATION TECHNOLOGY

- Founded 2002
 Center of excellence in research
 Member of CyberSecurity DIH
 Al education tradition
 - 1982 Robotics
 - 1988 Fundamentals of Al
 - 1998 Neural networks



WORKING WITH BEST

- Leading global companies
- Well-known universities
- World-class R&D centers and institutes
- National and International scientific projects





STRATEGIC R&D AREAS

- Information Technologies
- Artificial Intelligence
- Cybersecurity
- Cyberphysical Systems
- High Performance Computing



Key Research Groups



Tr FIT

Language Processing

(Doc. Dr. Cernocky)

Evolvable Hardware (Prof. Sekanina)

Accelerated Network Technologies (Dr. Korenek)

Automated Analysis and Verification (Prof. Vojnar)

Big Data / Knowledge Technology (Dr. Smrz) Computer Vision and Graphics (Prof. Zemcik, Prof. Herout)

Supercomputing Technologies (Dr. Jaros)

Computational Photography (Dr. Cadik)

Human-Machine Interaction & Robotics (Dr. Beran, Dr. Rozman)

> Security Technology R&D (Prof. Drahansky)



AUTONOMOUS MOBILITY @ FIT BUT



WHAT WE DO

AUTONOMOUS TECHNOLOGIES

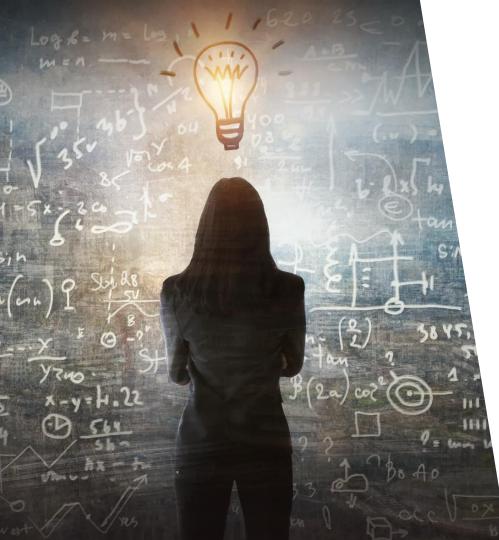
- AGV, Autonomous driving, Mobile robots
- Navigation and 3D mapping (SLAM/ PTAM)
- Vision technologies
- Data fusion, Sensors data processing
- User Interface

BIG DATA

- Deep & Machine learning
- Big-data, data mining, knowledge gathering

SECURITY

AND MANY MORE



INNOVATIVE PROJECTS





H2020 5G-ERA

ARTIN roboauto





BRING AUTO

- 5G Networks technology for autonomous driving
- Enhanced Robot Autonomy
- Selfdriving vehicle in operation
- Training of deep neural network
- Cloud Native (CN) approach, standardised APIs, integration of ROS with OSM



Lidar





Odometry Estimation from Velodyne LiDAR Point Cloud Scans

- A novel method of odometry
- Change in pose and orientation of the scanning device over time
- Deals with the sparsity and the quantity of data points
- Estimation a precise transformation aligning the two Velodyne scans (Collar Line Segments)

NANORADAR



An innovative nanoradar sensor for autonomous driving of trucks

• Radar technology

(2 autonomous driving functions)

- Mechanical design
- HW and SW aspects
- Automation and control
- Machine learning
- Signal processing
- Validation and testing

USER INTERFACE



ŠKODA

PROTOTYPING FRAMEWORK

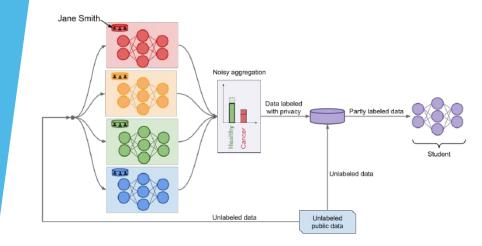
- Unique system allowing to design and validate new user interfaces for future cars easily
- Framework for dashboard / infotainment module / head-up display
- Shortening the development cycle to agile respond to the latest trends in HMI

"For the next period, we would like to continue working with experts from FIT BUT, especially in the field of innovations for autonomous mobility." *Vít Neruda, ŠKODA AUTO*

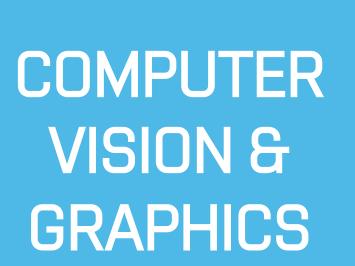
T FIT

SAFETY & SECURITY

- Trustworthiness of Al in autonomous driving
- Research on robustness guarantees for deep learning in an adversarial setting











- Object detection & recognition
- Fully automatic visual surveillance
- Camera systems
- Image processing
- HDR experiments
- Mapping technologies
- Detection, measurement, scaling

Our spin-offs / start-ups:

COGNITECHNA OGOCIOM

- Fully Automatic Visual Traffic Surveillance
- HDR & CV in Embedded HW
- Camera system automatic calibration
- Vehicle classification & reidentification
- License plate recognition
- Detection, measurement, scaling
- Real time object detection





T FIT

WE GO BEYOND

- Smart cities
- Applied from Cross-CPP project
- Learning from data streams
- Interconnected vehicles & Smart buildings & E-chargers & Hyperscale Weather forecast etc.



BIG DATA

- T FIT
- Data analysis & predictive maintenance
- Sensory data processing (audio, video, radars...)
- Deep & Machine learning
- Big-data, da<mark>ta</mark> mining, knowledge gathering
 - MindSphere technology

1500

- Cross-sectorial data stream
- Action recognition (invideo)

120

100

80

60 40

20

EVOLVABLE HARDWARE



- Best trade-offs between accuracy, performance and power consumption ML based on genetic programming Automatic design, optimization or approximation Digital circuits (FPGA, ASICs) and
- **Evolutionary circuit optimization** Circuit: Cordic (LGSynth93)

SW routines

23 inputs, 2 outputs Original: 106 gates After optimization: 39 gates



AUTOMATION

& ROBOTICS

- Navigation and 3D mapping reconstruction (SLAM/PTAM)
- UI for Remote Manipulation
- Close Human-Robot Interation & Cognition
- Virtual & Augmented Reality
- Data fusion
- Mobile robots, AGV, Autonomous driving

Let's work together

